

The Use of Principal Component Analysis (PCA) in Processing AIRS Data

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5. FUTURE WORK

1. INTRODUCTION

Atmospheric Infrared Sounder (AIRS) on the NASA EOS AQUA platform is providing much improved atmospheric temperature and moisture profiles when compared to soundings from current operational sounders. Principal Components Analysis (PCA) provides an effective way to approximate the AIRS observations. This poster presents the application of PCA to AIRS data, including the generation and application of eigenvectors, and the use of PCA for data compression, high noise channel detection and reconstruction, noise filtering and estimation, and regression retrieval.

2. METHOD

In our application the data vectors are radiance spectra that are divided by the expected instrumental noise, which we refer to as normalized radiances. The eigenvectors are related to the covariance matrix by:

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S = E 8E^T
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where S is a N x N covariance matrix. E is the matrix of eigenvectors, and 8 is the diagonal matrix of eigenvalues. The principal component scores P are computed from: $\mathbf{P} = \mathbf{E}^{\mathrm{T}} \mathbf{R}$

where R is the vector of centered normalized radiances. An overall estimate of how well the principal component scores can reconstruct the original data is provided by Reconstruction Score (RS), which is defined as:

 $RS = [1/N_3(O_i - R_i)^2]^{1/2}$

i=1...N channels, O and R are noise scaled observed and reconstructed radiances for ith channel.

Application 1: Reconstruct Radiance

Our studies indicate that AIRS brightness temperature can be reconstructed within the noise level, using about 80 eigenvectors.



3. APPLICATION 4. CONCLUSION We use the PCA to generate reconstructed radiances and to The knowledge that we are gaining from the AIRS data compute the RMS between the reconstructed radiances and the will be useful for high spectral infrared radiance data observed radiances. Principal component regression of near real time AIRS data processing and compression for future satellite observations. It appears for most cases that the RMS is comparable with the provides a very computational efficient retrieval of atmospheric Additional work to study noise filtering feature of eofs is instrument noise level. It implies that the AIRS observations temperature, moisture, and ozone, etc. needed. can be reconstructed very accurately by much less number of Principal component scores have been a very effective tool for To create a stable PCA operational system using as many PCS. data compression, detector monitoring and bad channel AIRS channels as possible. handling, as well as the noise estimation. ig 1 Top: A typical AIRS Spectrum; Lower left: Explained Variance vs. number of Use most correlated channels instead of neighboring genvectors; Lower right: Reconstruction score vs. number of eigenvectors channels for bad channel reconstruction. 300 **Application 3: Noise Estimate/Filtering Application 4: Regression Retrieval** 280 260 igure 3: shows impact of reconstructing radiance. This is a expanded view from a spectrally boring 240 32 ion 892 to 902. A retrieval would benefit from operating on the difference between purple and blue Use the first 85 PCS as predictors, generate regression stead of black and blue 220 retrievals of atmospheric temperature, moisture, ozone, and 200 1000 1500 2000 skin temperature black i riginal, blue is calculated from mode Wavenum Regression coefficients generated from June have been stable. eigenvector **Application 2: Channel Monitoring and Bad Channel Handling** Score (hefore had channel h core (after had cha In operational AIRS processing, when a channel has a bad radiance value, it has to be replaced by something useful since information from each channel is required to reconstruct the radiances Bad channel handling technique: when a bad channel is detected, use the neighboring channels to compute the pcs, and reconstruct the bad channel. Quality Flag Definitions: Good Quality Data; 2 – Reserved; 4 – Jndesirable Channel Properties; 8 – Bad Offset for Channel ; 16 - Bad Gain for Channel; 32 - Pop Detected in Channel; 64 – Bad Telemetry ; 128 – High Noise in Channel; 256 – The Instrumer in science mode: 512 – No data for this channel a standard and a stand





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