Combining GPS occultations with AIRS infrared measurements for improved atmospheric sounding

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Outline

- Introduction Motivation, Reminder
- Input data
- Combined retrieval method
- Results
- Conclusion & Future Plans







Geometry of radio occultation







Motivation

GPS/RO

-good absolute accuracy

-very high vertical resolution, poor horizontal resolution

- -information in upper troposphere and stratosphere
- -high accuracy around tropopause
- -"all weather" instrument

IR and MW (ATOVS)

-high horizontal resolution, poor vertical resolution

-information from the total atmospheric column

-more information on lower tropospheric temperature

-less information around the tropopause

Results of simulation study

Results of real ATOVS+CHAMP/SACC study





RMS/bias diff of simulated temp retrievals from various systems





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CIMS

RAOB validation of SACC + ATOVS T(p)

Oct 2001, Jan, Apr and July 2002



GPS/RO (SACC) data improves the radiometric (ATOVS) temp retrievals around the tropopause by 0.5 K (larger impact over the cloudy skies)





Input data

90° W

120[°] W

60°W 30°W

Time period: Sept 2002 - Oct 2003

AIRS+RAOB matchup (100,266 collocations)

GPS data (SAC-C) July 2001 and Dec 2003: 66,989 occultations

GPS data (CHAMP) May 2001 and Dec 2003: 106,609 occultations

AIRS+RAOB+GPS collocation:

1980 (382 clear sky)

AMSU (AQUA): v3.0.8.0

AIRS level 2: v3.0.8.0







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90°E 120°E 150°E 180°E

60[°] E

30 E

Method

Test of different cloud masks:

Clear: if BT(obs) –BT(calc) <= 7

for less than 10 selected channels



Test of different set of selected

channels and retireval methods:

- Clear sky PC statistical regression method number of PCs:30
- 6 BT and 11 scan angle classification
- with 1688 selected channels

Class	BT@1000 cm ⁻¹ training	BT@1000 cm ⁻¹ observations
1	BT ≤ 260	BT ≤ 255
2	250 <bt≤270< td=""><td>255<bt≤265< td=""></bt≤265<></td></bt≤270<>	255 <bt≤265< td=""></bt≤265<>
3	260 <bt≤280< td=""><td>265<bt≤275< td=""></bt≤275<></td></bt≤280<>	265 <bt≤275< td=""></bt≤275<>
4	270 <bt≤290< td=""><td>275<bt≤285< td=""></bt≤285<></td></bt≤290<>	275 <bt≤285< td=""></bt≤285<>
5	280 <bt≤300< td=""><td>285<bt≤295< td=""></bt≤295<></td></bt≤300<>	285 <bt≤295< td=""></bt≤295<>
6	290 < BT	295 < BT





AIRS+AMSU+GPS Clear Sky retrieval

Regression Retrieval of T, q, O3, Ts, Ps, and ε_s under clear conditions

Regression Model

$$X = C Y$$

Least squares regression solution

 $C = X Y^{T} (Y Y^{T})^{-1}$

X...Atmospheric State,

C...Coefficients,

Y...Measurements: AIRS & AMSU BTs and GPS refractivity profiles

Forward Model Calculations AIRS BTs: SARTA model

AMSU BTs: Paul van Delst's implementation of Liebe MPM line-by-line model (Channels: 6-14)

GPS refractivity profiles: (Healy & Eyre, 2000) with vertically correlated measurements errors (200m vertical resolution)





POSTER IIII Training Data

12,245 global atmospheric profiles
Profiles are taken from the NOAA-88, ECMWF training set, TIGR-3, ozonesondes, desert radiosondes
All with saturation checks and other QC
New Surface Skin Temperature assigned to profiles
New ecosystem-based Surface Emissivity assigned to profiles







Electrochemical concentration cell (ECC) Ozonesondes weekly launches, 1997 to present at 8 sites through the Climate Monitoring and Diagnostics Laboratory (CMDL)





RAOB validation of AIRS+AMSU retrievals with and without GPS data



GPS between 8 and 26 km





RAOB validation of AIRS+AMSU retrievals with and without GPS data



GPS between 1 and 26 km (3Xo3Xnoise)



CIMSS

Comparison of temperature profiles





Comparison of temperature profiles





Comparison of moisture profiles





Comparison of moisture profiles





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Conclusions

In clear sky conditions, AIRS L2 v3 temperature retrievals perform better than AIRS+AMSU regression retrievals but worse than AIRS+AMSU+GPS. The part of the atmosphere that shows the greatest improvement from inclusion of GPS is the tropopause.

For moisture, AIRS L2 is the best, followed by AIRS+AMSU+GPS and last is AIRS+AMSU (without GPS)

Future Plans

- •Expand the dataset with more collocations
- •Investigate the lower troposphere more
- •Compare with operational AIRS L2 retrievals when v4 is available
- •Use v4 software to integrate GPS (if source code becomes available)
- •Integrate GPS data in cloudy retrievals









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